

Sheaves for Children

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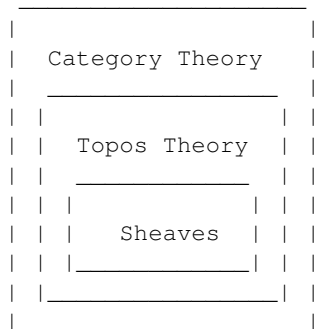
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<http://angg.twu.net/math-b.html>
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Where sheaves stand



Cartesian Closed Categories,
Lambda-Calculus,
Intuitionistic Logic

Modal Logic (S4)

Topology

Algebraic Geometry

CT: Why?

Category Theory is fascinating (for some people!),
but (usually) too abstract...

The right level of abstraction
makes lots of proofs *almost* automatic:
proving something in CT means
constructing something (CT is constructive!), and
all “natural” constructions are equivalent (“coherence”).

More or less like this:

Let A and B be (arbitrary) sets.

Then there is an “obvious” function $\text{flip} : A \times B \rightarrow B \times A$.

This *ought* to make some parts of CT *easy!!!*

(Long story... see “Internal Diagrams and Archetypal Reasoning in
Category Theory”)

Why study CT *now*?



Public education in Brazil is being dismantled -
maybe we should be doing better things than studying
very technical & inaccessible subjects
with no research grants -

Category theory should be more accessible

Most texts about CT are for specialists in research universities...

Category theory should be more accessible.

To whom?...

- Non-specialists (in research universities)
- Grad students (in research universities)
- Undergrads (in research universities)
- Non-specialists (in conferences - where we have to be quick)
- Undergrads (e.g., in CompSci - in teaching colleges) - (“Children”)

ZSets

Take a finite, non-empty subset of \mathbb{N}^2 ;
translate it lowerleftwards as most as possible in \mathbb{N}^2 ,
until you get something that touches both axes.

Subsets of \mathbb{N}^2 obtained in this way are said to be
“well-positioned”, and we call them *ZSets*.

We can use a positional notation with bullets
to denote our favourite ZSets (unambiguously!)

<i>V</i>	Vee	••	$\{(0, 1), (2, 1), (1, 0)\}$
<i>K</i>	Kite	•••	$\{(1, 3), (0, 2), (2, 2), (1, 1), (1, 0)\}$
<i>H</i>	House	•••	$\{(1, 2), (0, 2), (2, 2), (0, 1), (2, 1)\}$

↑ Some of my favorite ZSets -
note that they have both short, one-letter names
and long, pronounceable names.

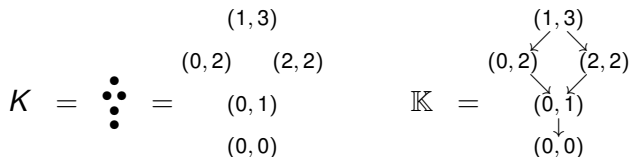
ZDAGs

An arrow between points of \mathbb{N}^2 that goes one unit down and 0/1/-1 units horizontally is called a *black pawn's move*.

Take a ZSet, D , and draw all possible black pawns moves between its points; this gives us a set of arrows, $\text{BPM}(D)$, that turns D , a ZSet, into a directed, acyclical, graph, \mathbb{D} , in a canonical way: $\mathbb{D} = (D, \text{BPM}(D))$.

Note the change of font!!!: $D \dashrightarrow \mathbb{D}$

Example:

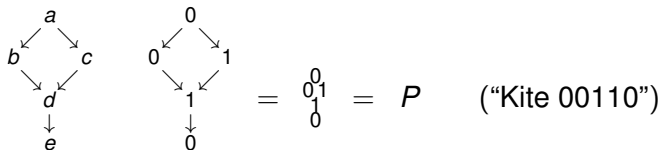


Truth-values

A function from a ZSet D to $\{0, 1\}$ is a *modal truth-value*.

The positional notation gives us a way to write modal truth-values very compactly, and the points on a ZSet have a natural order - the “reading order”, in which we read them line by line, left to right in each line.

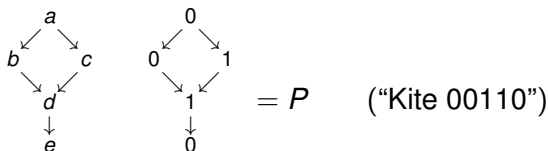
This gives us a way to *read aloud* modal truth-values - and to list all modal truth-values in order.



Notation: $\mathcal{P}(\mathbb{D})$ is the set of modal truth-values on \mathbb{D}

We use “ $\mathcal{P}(\mathbb{D})$ ” because 00110 “is” $\{c, d\} (\subset K)$

Intuitionistic truth-values



Now consider that each 1 in P is covered with (wet) black paint. Then P ("Kite 00110") is not *stable*, because the paint of the 1 in position d will flow down into the 0 of position e , and paint it black.

Stable modal truth-values are called *intuitionistic truth-values*.

Notation: $\downarrow P$ is P after letting the black paint flow down.

Example: $\downarrow \begin{matrix} 0 & 1 \\ 1 & 1 \\ 0 & \end{matrix} = \begin{matrix} 0 & 1 \\ 1 & 1 \\ \downarrow & \end{matrix}$

The order topology

$$\downarrow \begin{matrix} 0 \\ 0 & 1 \\ 0 \end{matrix} = \begin{matrix} 0 \\ 0 & 1 \\ 1 \end{matrix}$$

Notation: $\mathcal{P}(\mathbb{D})$ is the set of modal truth-values on \mathbb{D}

Notation: $\mathcal{O}(\mathbb{D})$ is the set of intuitionistic truth-values on \mathbb{D}

$$\downarrow : \mathcal{P}(\mathbb{D}) \rightarrow \mathcal{O}(\mathbb{D})$$

The topology $\mathcal{O}(\mathbb{D})$ is the *order topology* -
an arrow $\alpha \rightarrow \beta$ in \mathbb{D} means that
if an open set contains α it has to contain β too.

(Order topologies are Alexandroff.)

Priming

Amazing fact: very often $\mathcal{O}(\mathbb{D})$ can be represented as a ZDAG too!

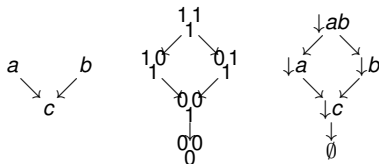
$\mathcal{O}(\mathbb{D})$ has a natural order:

$P \rightarrow Q$ means $P \leq Q$, $P \subseteq Q$, $P \vdash Q$,

and $\top = 1_1$ ("Top") is the terminal of the category...

But if we draw $\mathcal{O}(\mathbb{D})^{\text{op}}$ instead of $\mathcal{O}(\mathbb{D})$

we can see clearly how $\mathbb{D} \hookrightarrow \mathcal{O}(\mathbb{D})^{\text{op}}$:



Note that $\downarrow ab = \downarrow \{a, b\} = \downarrow 1_0^1 = 1_1^1$.

Def: $\mathbb{D}' = \mathcal{O}(\mathbb{D})^{\text{op}}$.

$\mathbb{V}' \cong \mathbb{K}$ - and, by abuse of language, $\mathbb{V}' = \mathbb{K}$.

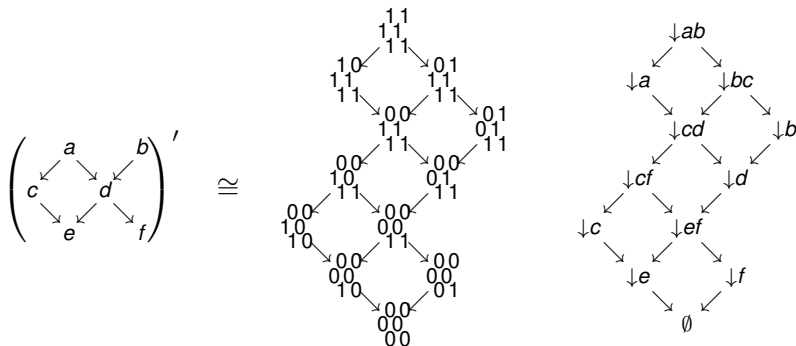
Unpriming

If $\mathbb{C}' = \mathbb{D}$ can we recover \mathbb{C} from \mathbb{D} ?

Better: if \mathbb{D} is a ZDAG that is a Heyting algebra can we find a $\mathbb{C} \subset \mathbb{D}$ such that $\mathbb{C}' = \mathbb{D}$?

Can we use that to determine quickly whether an arbitrary \mathbb{D} is a Heyting algebra?

Yes, yes, & yes!



Priming: theorems

We say that \mathbb{D} is *3-thin* when $\bullet\bullet\bullet \notin \mathbb{D}$.

We say that \mathbb{D} is *square-thin* when $\bullet\bullet \notin \mathbb{D}$.

We say that \mathbb{D} is *thin* when it is both 3-thin and square-thin.

Fact: if \mathbb{D} is 3-thin then \mathbb{D}' is a ZDAG.

Fact: if \mathbb{D} is thin then \mathbb{D}' is a thin ZDAG.

Fact: every topology - whether planar or not - is a Heyting algebra - i.e., we can interpret $T, F, \wedge, \vee, \rightarrow, \neg$ on it, and every \mathbb{D}' is a topology...

Priming gives us LOTS of Heyting algebras,
and lots of *planar* Heyting algebras!

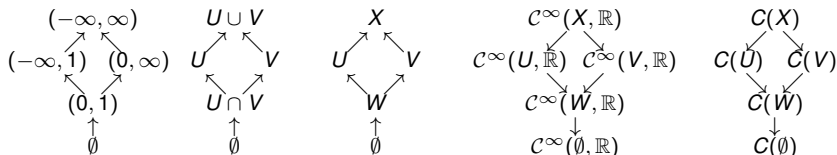
Topological sheaves are defined on diagrams like $\mathbb{D} \hookrightarrow \mathbb{D}' \hookrightarrow \mathbb{D}''$.

Glueing locally-defined functions

Let U be $(-\infty, 1)$

and V be $(0, \infty)$...

Consider these open sets in \mathbb{R} ,



and the sheaf C of C^∞ functions from them to \mathbb{R} .

Upward arrows are *inclusions* (of an open set into another).

Downward arrows are *restrictions* (of domains).

Two functions f_U and f_V are *compatible*

if their restrictions to $U \cap V$ coincide.

Each compatible family $\{f_U, f_V\}$ in C has a unique glueing f_X .

Generalize that, and you get the definition of *sheafness*.

Sheafness

A compatible family $\{f_U, f_V\}$ is defined on $\{U, V\} = \begin{smallmatrix} 0 \\ 1 \ 0 \end{smallmatrix}$,
and it can be extended, using the restriction maps $\rho_{UV} : FU \rightarrow FV$
etc,

to a downward-closed compatible family $\{f_U, f_V, f_W, f_\emptyset\}$,
defined on $\{U, V, W, \emptyset\} = \begin{smallmatrix} 0 \\ 1 \ 1 \end{smallmatrix} \dots$

The “unique glueing” f_X of $\{f_U, f_V\}$ can be extended
to a downward-closed compatible family $\{f_X, f_U, f_V, f_W, f_\emptyset\}$,
defined on $\{X, U, V, W, \emptyset\} = \begin{smallmatrix} 1 \\ 1 \end{smallmatrix}$.

The restriction

$$\{f_X, f_U, f_V, f_W, f_\emptyset\} \xrightarrow{\rho} \{f_U, f_V, f_W, f_\emptyset\}$$

is trivial to define -

sheafness means that maps like these are bijections.

Topological sheafness

A closure operator:

$$\sqcup\{U, V, W, \emptyset\} = \{X, U, V, W, \emptyset\}$$

it takes the union $U \cup V \cup W \cup \emptyset = X$

and then all subsets of that.

It acts on \mathbb{V}'' : $\sqcup : \bullet\bullet'' \rightarrow \bullet\bullet''$

$$\sqcup \begin{matrix} 0 \\ 1 \\ 1 \\ 1 \end{matrix} = \begin{matrix} 1 \\ 1 \\ 1 \\ 1 \end{matrix}$$

Which elements of \mathbb{V}'' are stable by \sqcup ?

Only $\downarrow\{U, V\} \mapsto \downarrow\{X\}$ ($\begin{matrix} 0 \\ 1 \\ 1 \end{matrix} \mapsto \begin{matrix} 1 \\ 1 \\ 1 \end{matrix}$) and $\emptyset \mapsto \{\emptyset\}$ ($\begin{matrix} 0 \\ 0 \\ 0 \end{matrix} \mapsto \begin{matrix} 0 \\ 0 \\ 0 \end{matrix}$)

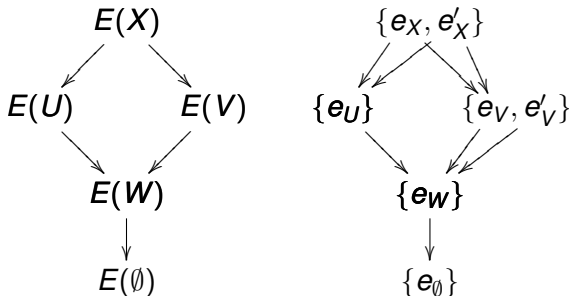
are *not* stable by \sqcup .

The stable elements of \mathbb{V}'' are these: $\begin{matrix} 1 \\ 0 \\ 1 \\ 1 \\ 0 \end{matrix}$.

These diagrams of stable elements are what we need to define sheaves “in general”.

The evil presheaf

A presheaf F in $\mathbf{Set}^{\mathcal{O}(\mathbb{V})^{\text{op}}}$
is simply a functor $F : \mathcal{O}(\mathbb{V})^{\text{op}} \rightarrow \mathbf{Set}$.



The **evil presheaf** $E : \mathcal{O}(\mathbb{V})^{\text{op}} \rightarrow \mathbf{Set}$, above,
fails to be in a sheaf in two ways:
the compatible family $\{e_U, e_V\}$ has two different glueings,
the compatible family $\{e_U, e'_V\}$ doesn't have a glueing.

Dual operations

Due to we being in a finite / planar / etc case, several interesting operations have duals (adjoints):

- In finite DAGs the transitive-reflexive closure $(A, R) \mapsto (A, R^*)$ has an adjoint that keeps only the “essential arrows” of the graph;
- The “let the paint flow down” operation $\downarrow \begin{smallmatrix} 0 & \\ 1 & \end{smallmatrix} = \begin{smallmatrix} 0 & \\ 1 & \end{smallmatrix}$ has an adjoint $\begin{smallmatrix} 0 & \\ 1 & \end{smallmatrix} \mapsto \begin{smallmatrix} 0 & \\ 0 & \end{smallmatrix}$ that returns the “generators” of an open set;
- Each closure operator like $\mathcal{U} \mapsto \sqcup \mathcal{U}$ has an adjoint that returns the smallest equivalent cover...

Where are the theorems?

Not here! Why???

Because this is “for children” -

we are focusing on the tools to let people check particular cases... and this *complements* [Bell 1988] and my IDARCT paper, that explains how to do theorems and archetypal cases in parallel

Slightly more advanced things:

- CCCs and Heyting Algebras; $(\wedge Q) \dashv (Q \rightarrow)$
- presheaves of the form $\mathbf{Set}^{\mathbb{D}}$ as toposes
- the classifier object of a $\mathbf{Set}^{\mathbb{D}}$
- other modalities (besides \sqcup) in a $\mathbf{Set}^{\mathbb{D}}$
- all logical properties of modalities follow from three axioms
- operations on the lattice of modalities
- forcing
- sheafification
- geometric morphisms between toposes - I need help here = (

For Further Reading I



J.L. Bell.

Toposes and Local Set Theories.
Oxford, 1988 (re-ed: Dover, 2007).



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Internal Diagrams and Archetypal Reasoning in Category Theory
Logica Universalis, 2013
<http://angg.twu.net/math-b.html>.